# Al Studio@RITS

Tech Social-February 2019





- My name is Sanaz Bayandor Jabbari
- Software engineering
  - Application of Reinforcement learning in Robocup



- Phd in computer science University of Sheffield
  - Statistical Natural language processing, Bayesian perspective



- Leading the R&D team at a tech start-up (Fizzback Ltd)
  - Sentiment analysis and classification of reviews across industries



- Applied computer scientist at Microsoft London
  - Bing, Outlook and Query formulation team

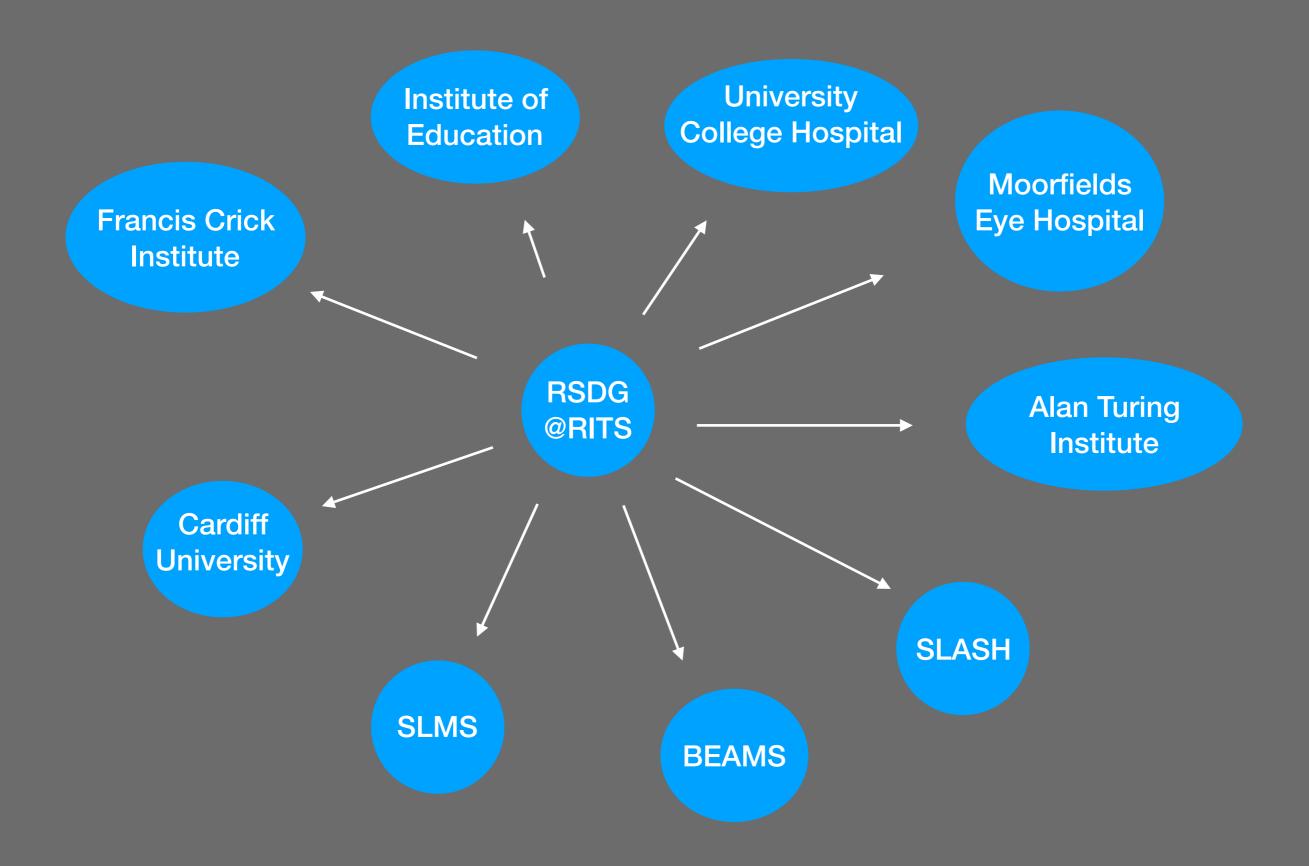


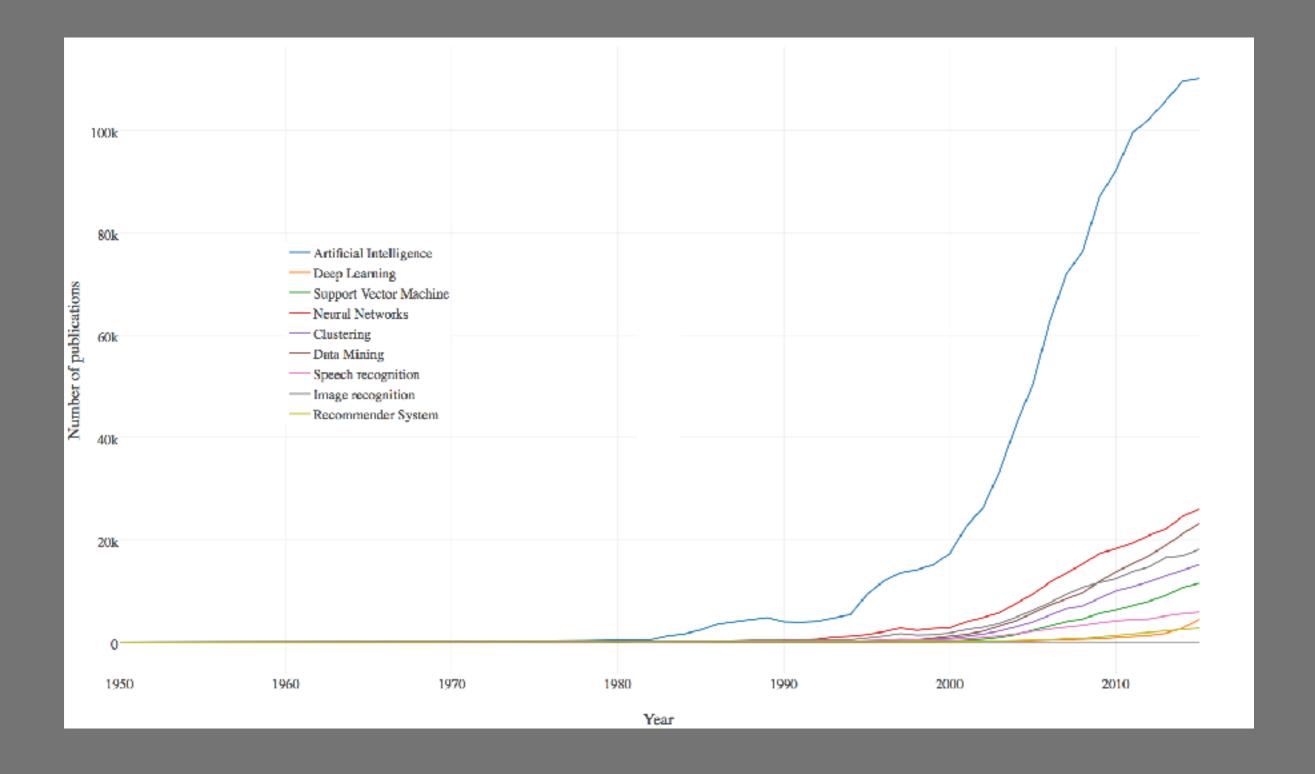
Al Studio lead at UCL's Research IT Services

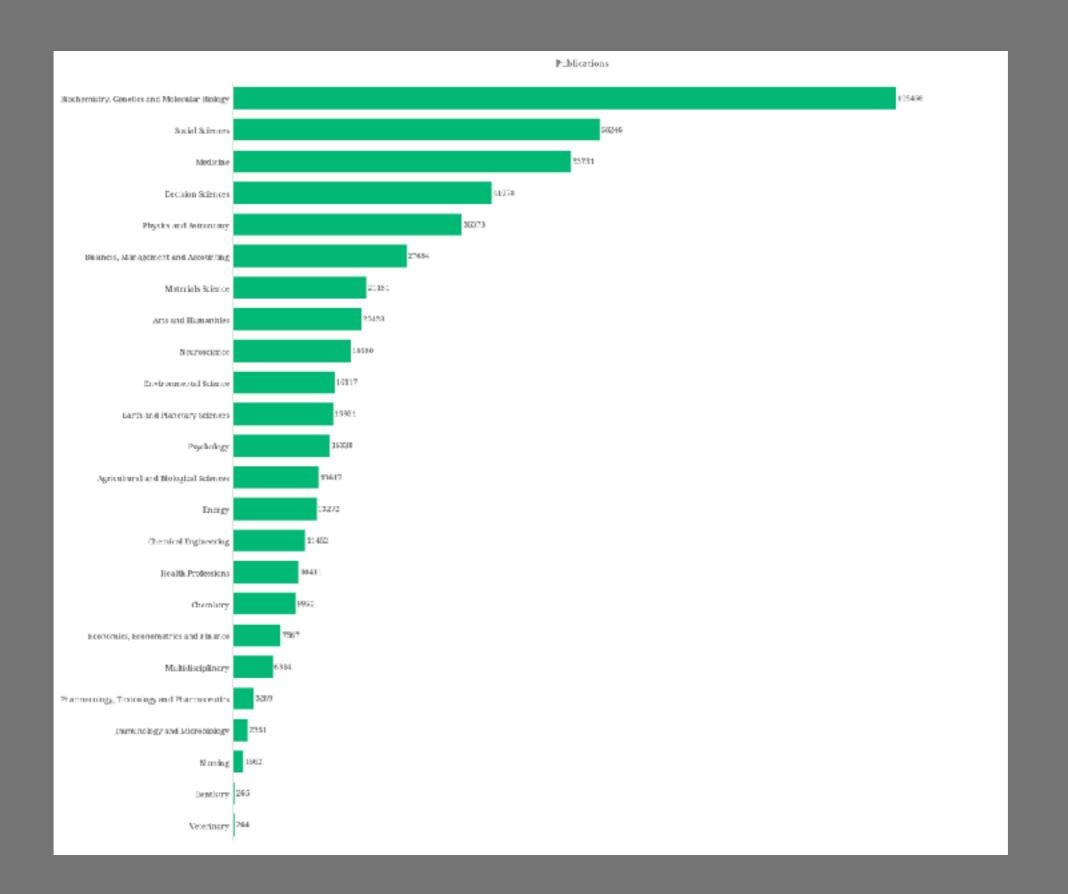
#### RSDG + Al Studio

- It's a part of Research Software Development Group at RITS
  - High quality research software
  - Combine academic research experience + software engineering
  - Producing software on behalf of researchers (Refactoring, Testing, Support their codes)
  - Work collaboratively
  - Providing the tools, advice and training researchers
- RSDG launched Al Studio in March 2018
  - To provide Data science/Machine Learning and Al services

### RSDG collaborations:







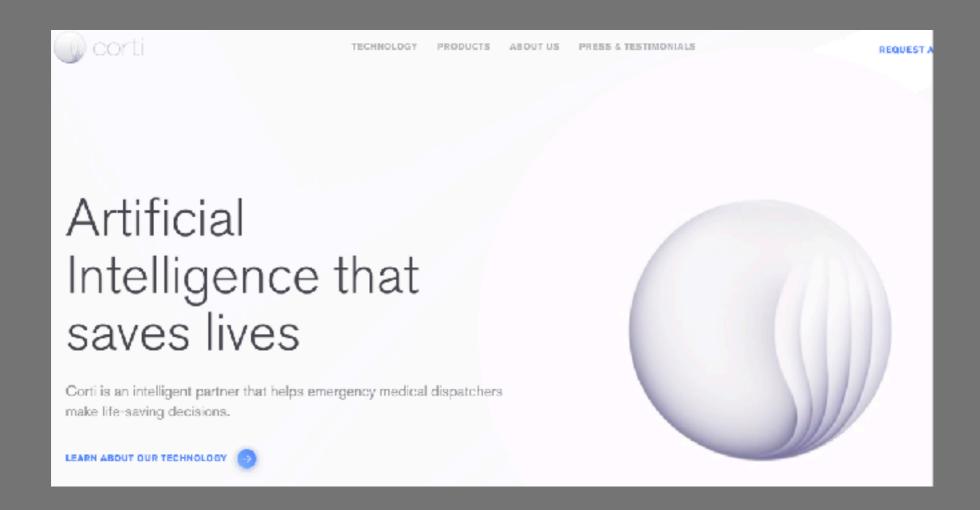
#### Al in Healthcare

- 1. Efficient Diagnosis and Clinical Judgement
  - Incomplete medical histories and large case load
  - In 2015, misdiagnosing illness accounted for 10% of all US deaths.
- 2. Al-Assisted Robotics Surgery
  - Da vinci
- 3. Virtual Nursing assistants
  - Care Angel, 24/7, save billions for industry
- 4. Image analysis
- 5. Administrative tasks and improving workflow
  - •A 2016 study in USA revealed 96% of patient complains over customer service, confusion over paperwork and negative front desk experience

# <u>CAMELYON challenge:</u> Diagnostic Image Analysis Group + Radboud University Medical Centre

- A training data set of whole-slide images "with/without (110/160)"
- Evaluated by a panel of 11 pathologists
- Deep learning models diagnosed breast cancer at a better rate than 11 pathologists.

Codename <sup>b</sup>	Task 1: Metastasis Identification FROC Score (95% CI) <sup>c</sup>	Task 2: Metastases Classification AUC (95% CI) <sup>c</sup>	P Value for Comparison of the Algorithm vs Pathologists WTC <sup>4</sup>	Algorithm Model		
				Deep Learning	Architecture	Comments
HMS and MIT II	0.807 (0.732-0.889)	0.994 (0.983-0.999)	<.001	<b>J</b>	GoogLeNet <sup>24</sup>	Ensemble of 2 networks; stain standardization; extensive data augmentation; hard negative minin
HMS and MGH III	0.760 (0.692-0.857)	0.976 (0.941-0.999	<.001	-	ResNet <sup>25</sup>	Fine-tuned pretrained network; fully convolutional network
HMS and MGH I	0.596 (0.578-0.734)	0.964 (0.928-0.989)	<.001	-	GoogLeNet <sup>24</sup>	Fine-tuned pretrained network
CULab III	0.703 (0.605-0.799)	0.940 (0.888-0.980)	<.001	~	VGG-16 <sup>26</sup>	Fine-tuned pretrained network; fully convolutional network
HMS and MIT I	0.693 (0.600-0.819)	0.923 (0.855-0.977)	.11	<b>"</b>	GoogLeNet <sup>24</sup>	Ensemble of 2 networks; hard negative mining
ExB I	0.511 (0.363-0.620)	0.916 (0.858-0.962)	.02	-	ResNet <sup>25</sup>	Varied class balance during training
CULab I	0.544 (0.467-0.629)	0.909 (0.851-0.954)	.04	<b>_</b>	VGG-Net <sup>26</sup>	Fine-tuned pretrained network



- A Danish Al software company detects cardiac arrests
- · By Analysing what a person says, the tone of voice and background noise
- keywords in the caller's description, faint background sounds
- Corti can identify patterns of anomalies or conditions of interest
- 93% success rate compared to 73% for human
- Reduce the number of undetected OHCAs by more than 50%





- Da Vinci Robotic Prostatectomy
- UCH team to do 600 prostate operations a year
- immersive 3D vision
- getting lots of information, little distraction
- no hand tremor, no limitation in terms of fatigue

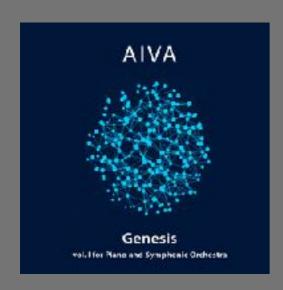


- Asks simple questions in a conversational manner
- Gather information about physical and emotional well-being
- Measures that includes medication adherence and overall vitals
- The answers are converted to simple Dashboard Notifications, Alerts and reports



- Two distinct problems in drug discovery: "biology and chemistry"
- Biology problem: decide which disease protein is the best one to target
- Chemistry problem: how to deliver a non-toxic molecule that can hit the chosen disease protein
- They developed a neural network called AtomNet, which helps in bioactivity prediction and identifying characteristics of patients for clinical trials.
- Tackles diseases like Ebola and multiple sclerosis.

#### Al in Art



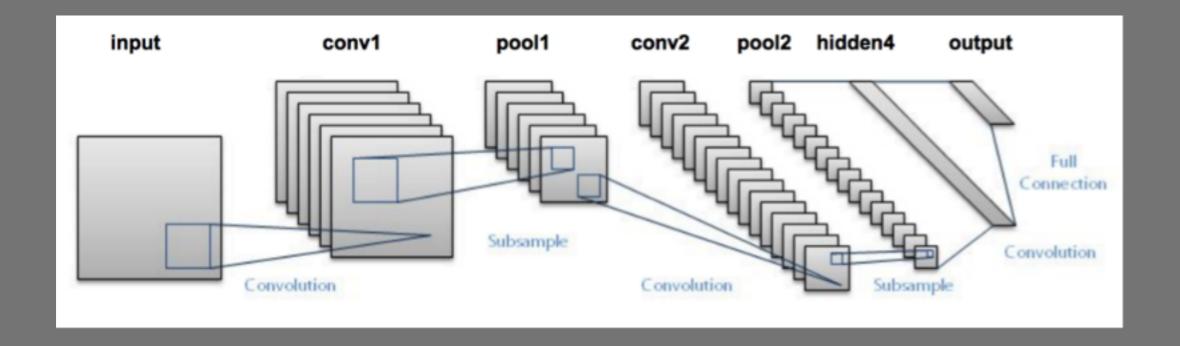
- Al composer that Learns from Mozart Bach, etc.
- Learned its own models of music theory
- Whether you are an amateur or a seasoned professional, AIVA assists you in creative process.
- Uses a combination of Deep learning models and Reinforcement Learning

#### Google Deep Dream



Generates
Psychedelic looking
images using CNN

- A base image is used
- Fed to the pre-trained CNN
- Forward pass is done till a particular layer
- Gaussian blurring to produce smooth images

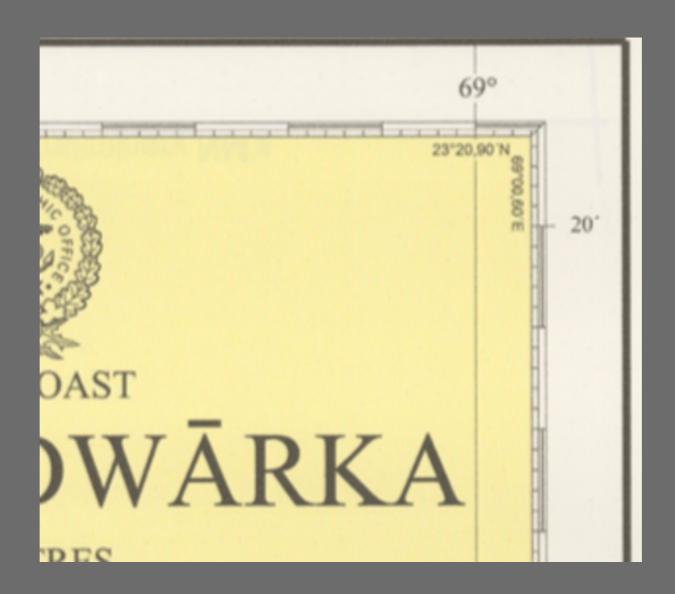


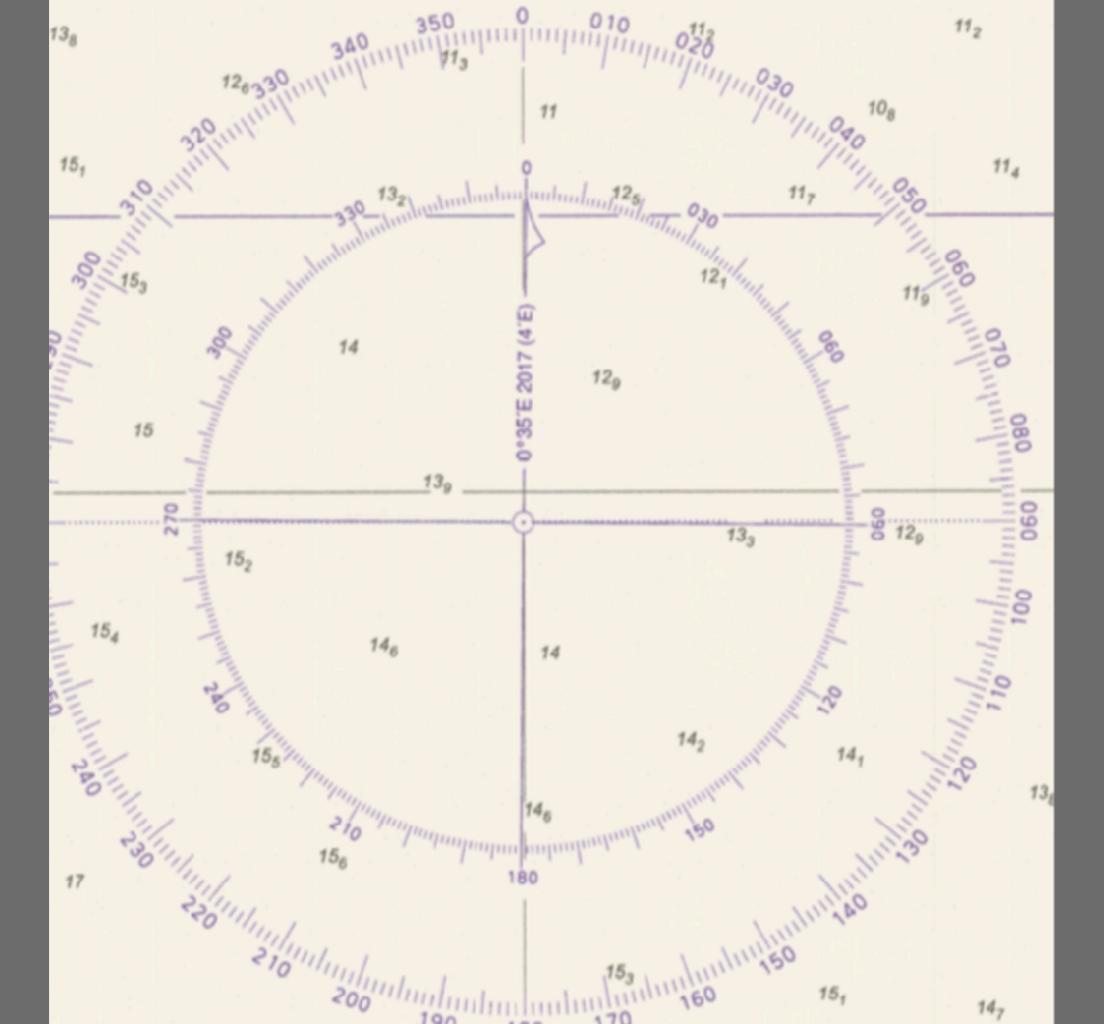
### Al in Digital Humanities

- Developing data-led approaches to answer research questions in the Humanities
- Analysis of our past and present societies
- •Use of "Word Embeddings" in NLP:
  - ★ Used in web search and machine translation, works by building up a mathematical representation of language
  - \*ability to reproduce complex and nuanced word associations
- Challenge: Al programs exhibit racial and gender biases
  - \*Machine learning algorithms are picking up deeply ingrained race and gender prejudices concealed within the patterns of language us

### OCR for Maps

- Funded by Department of Statistics (PI: Serge Guilas)
- Develop a Model to forecast effects of Tsunamis in the coasts of India, and to some extent Pakistan and Iran
- They were using bathymetry data within very low resolution (about 1km), but have now access to scans of maps of 50-90m resolution.
- Al Studio: To extract Bathymetry information from scanned paper maps







#### Automatic extraction of Bathymetry information

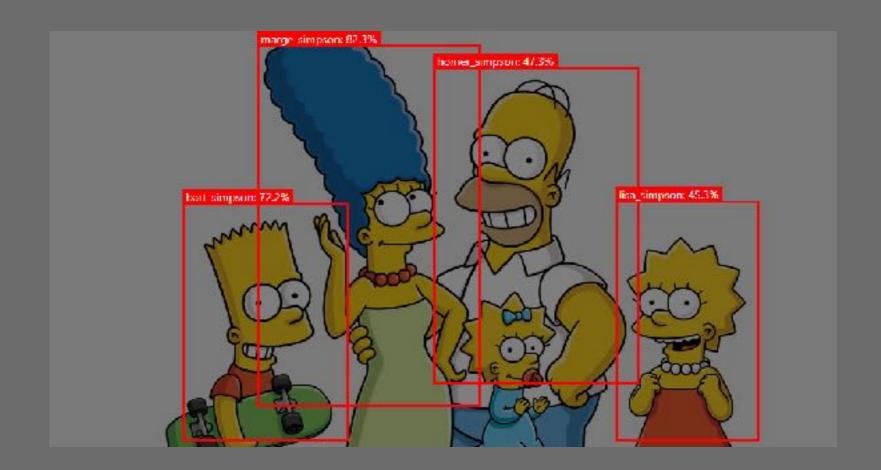
- 1. Localisation/Object(Bathymetry) Detection
- 2. Transform Normalised coordinates of the bounding box to pixel values
- 3. Digit detection (OCR)
- 4. Final Mapping to Geographical Information System (GIS)

#### Microsoft Azure Custom Vision service API

- The Azure Custom Vision API is a cognitive service that lets you build, deploy and improve custom image classifiers.
- It provides a REST API and a web interface to upload your images and train the classifier.
  - Step 1: Create a Custom Vision Service project
  - Step 2: Upload images to the project
  - Step 3: Train the project
  - Step 4: Get and use the default prediction endpoint

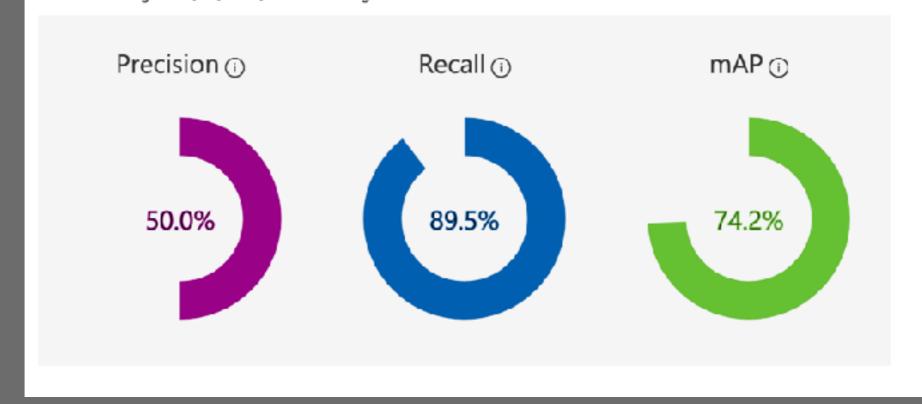
### **Object Detection Algorithms**

	Algorithm	Features	Prediction time / image	Limitations
	CNN	Divides the image into multiple regions and them classifies each region into various class//s.	-	Needs a lot of regions to predict accurately and hence high computation time.
	R-CNN	Uses selective search to generate regions. Extracts around 2000 regions from each image.	40-50 seconds	High computation time as each region is passed to the CNN separately. Also, it uses three different models for making predictions.
	Fast R- CNN	Each image is passed only once to the CNN and feature maps are extracted. Selective search is used on these maps to generate predictions.  Combines all the three models used in R-CNN together.	2 seconds	Selective search is slow and hence computation time is still high.
	Faster R- CNN	Replaces the selective search method with region proposal network (RPN) which makes the algorithm much faster.	0.2 seconds	Object proposal takes time and as there are different systems working one after the other, the performance of systems depends on how the previous system has performed.



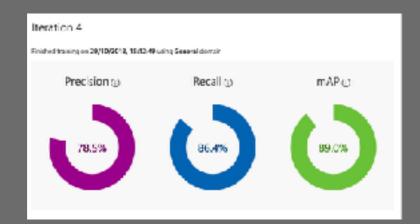
#### Iteration 1

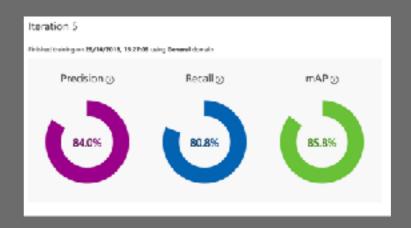
Finished training on 28/10/2018, 17:30:36 using General domain



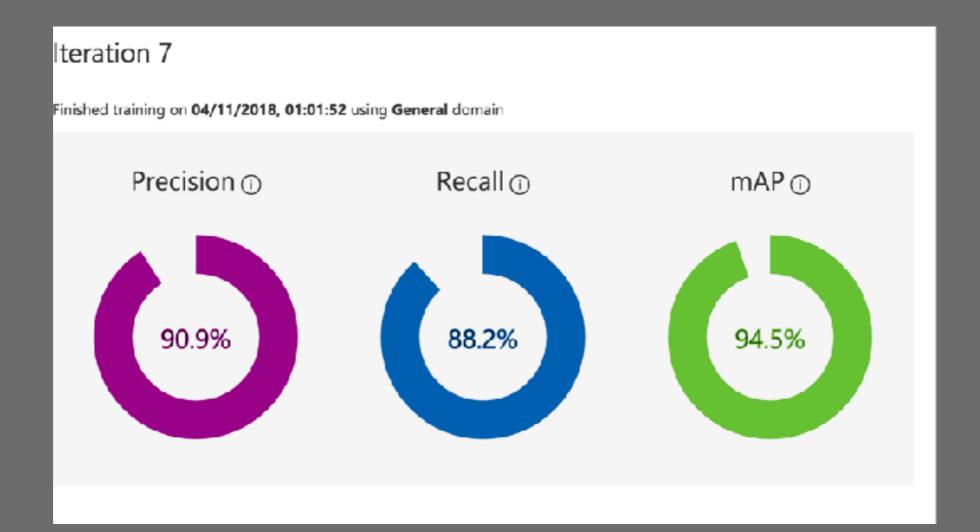












```
[]: from azure.cognitiveservices.vision.customvision.training import training api
   from azure.cognitiveservices.vision.customvision.training.models import ImageUrlCreateEntry
]: training key = "Oafd80975f7d4bcfbf41091025f63d18"
   prediction key = "494e7450f6c84f5cab9a19f15aacb8c7"
1: trainer = training api.TrainingApi(training key)
]: # Find the object detection domain
   obj detection domain = next(domain for domain in trainer.get domains() if domain.type == "ObjectDetection")
1: from azure.cognitiveservices.vision.customvision.prediction import prediction endpoint
   from azure.cognitiveservices.vision.customvision.prediction.prediction endpoint import models
1: # Now there is a trained endpoint that can be used to make a prediction
   predictor = prediction_endpoint.PredictionEndpoint(prediction_key)
]: print(predictor)
   <azure.cognitiveservices.vision.customvision.prediction.prediction_endpoint.PredictionEndpoint object at 0x106329c18>
1: # Open the sample image and get back the prediction results.
   with open("Desktop/Map-data/test.png", mode="rb") as test data:
       results = predictor.predict image("94cc37fa-2c33-46a6-bec0-4812ee6756e8", test data, 9)
]: # The results include a prediction for each tag, in descending order of probability - so we'll get the first one
   prediction = results.predictions[0].tag_name + ": {0:.2f}%".format(results.predictions[0].probability * 100)
]: prob threshold = 30
   for prediction in results.predictions:
       if(prediction.probability * 100 > prob threshold):
           print ("\t" + prediction.tag name + ": {0:.2f}%".format(prediction.probability * 100), prediction.bounding box.
```

```
bathymetry: 84.47% 0.3687336 0.113785833 0.0427250564 0.06949571
bathymetry: 74.86% 0.893987834 0.05414215 0.03965074 0.07409763
bathymetry: 78.97% 0.05917628 0.18522799 0.0407806337 0.07265636
bathymetry: 51.88% 0.67333734 0.242517665 0.0381319523 0.0492717177
bathymetry: 77.72% 0.7625825 0.294527322 0.0403059721 0.05681169
bathymetry: 84.83% 0.200847253 0.390882343 0.0444975942 0.06986123
bathymetry: 62.79% 0.0 0.580588639 0.0334429145 0.06744242
bathymetry: 83.95% 0.312596381 0.66159004 0.0374214649 0.05937451
bathymetry: 49.13% 0.56536 0.7049216 0.04560536 0.0614088774
bathymetry: 64.97% 0.713270664 0.707325041 0.0405855775 0.0699597
bathymetry: 87.68% 0.146008015 0.878702 0.0421329439 0.06535214
bathymetry: 69.06% 0.4692494 0.8771325 0.0378058851 0.0607491136
bathymetry: 85.89% 0.8516862 0.865169942 0.04507923 0.06342441
```

## Digit classification

- Azure's Computer Vision's optical character recognition (OCR) feature detects text content in an image.
- MNIST dataset, train a deep learning model using tensor flow and keras
- Image processing with OpenCV library:
  - Template Matching!!

### OpenCV and template matching

- To find objects in an image using Template Matching
- You will see these functions : cv2.matchTemplate()

```
import cv2
import numpy as np
from matplotlib import pyplot as plt

img_rgb = cv2.imread('mario.png')
img_gray = cv2.cvtColor(img_rgb, cv2.COLOR_BGR2GRAY)
template = cv2.imread('mario_coin.png',0)
w, h = template.shape[::-1]

res = cv2.matchTemplate(img_gray,template,cv2.TM_CCOEFF_NORMED)
threshold = 0.8
loc = np.where( res >= threshold)
for pt in zip(*loc[::-1]):
    cv2.rectangle(img_rgb, pt, (pt[0] + w, pt[1] + h), (0,0,255), 2)

cv2.imwrite('res.png',img_rgb)
```

Enumerator	
TM_SQDIFF Python: cv.TM_SQDIFF	$R(x,y) = \sum_{x',y'} (T(x',y') - I(x+x',y+y'))^2$
TM_SQDIFF_NORMED Python: cv.TM_SQDIFF_NORMED	$R(x,y) = \frac{\sum_{x',y'} (T(x',y') - I(x+x',y+y'))^2}{\sqrt{\sum_{x',y'} T(x',y')^2 \cdot \sum_{x',y'} I(x+x',y+y')^2}}$
TM_CCORR Python: cv.TM_CCORR	$R(x,y) = \sum_{x',y'} (T(x',y') \cdot I(x+x',y+y'))$
TM_CCORR_NORMED Python: cv.TM_CCORR_NORMED	$R(x,y) = \frac{\sum_{x',y'} (T(x',y') \cdot I(x+x',y+y'))}{\sqrt{\sum_{x',y'} T(x',y')^2 \cdot \sum_{x',y'} I(x+x',y+y')^2}}$
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TM_CCOEFF_NORMED Python: cv.TM_CCOEFF_NORMED	$R(x,y) = \frac{\sum_{x',y'} (T'(x',y') \cdot I'(x+x',y+y'))}{\sqrt{\sum_{x',y'} T'(x',y')^2 \cdot \sum_{x',y'} I'(x+x',y+y')^2}}$

### OCR Maps using opency:

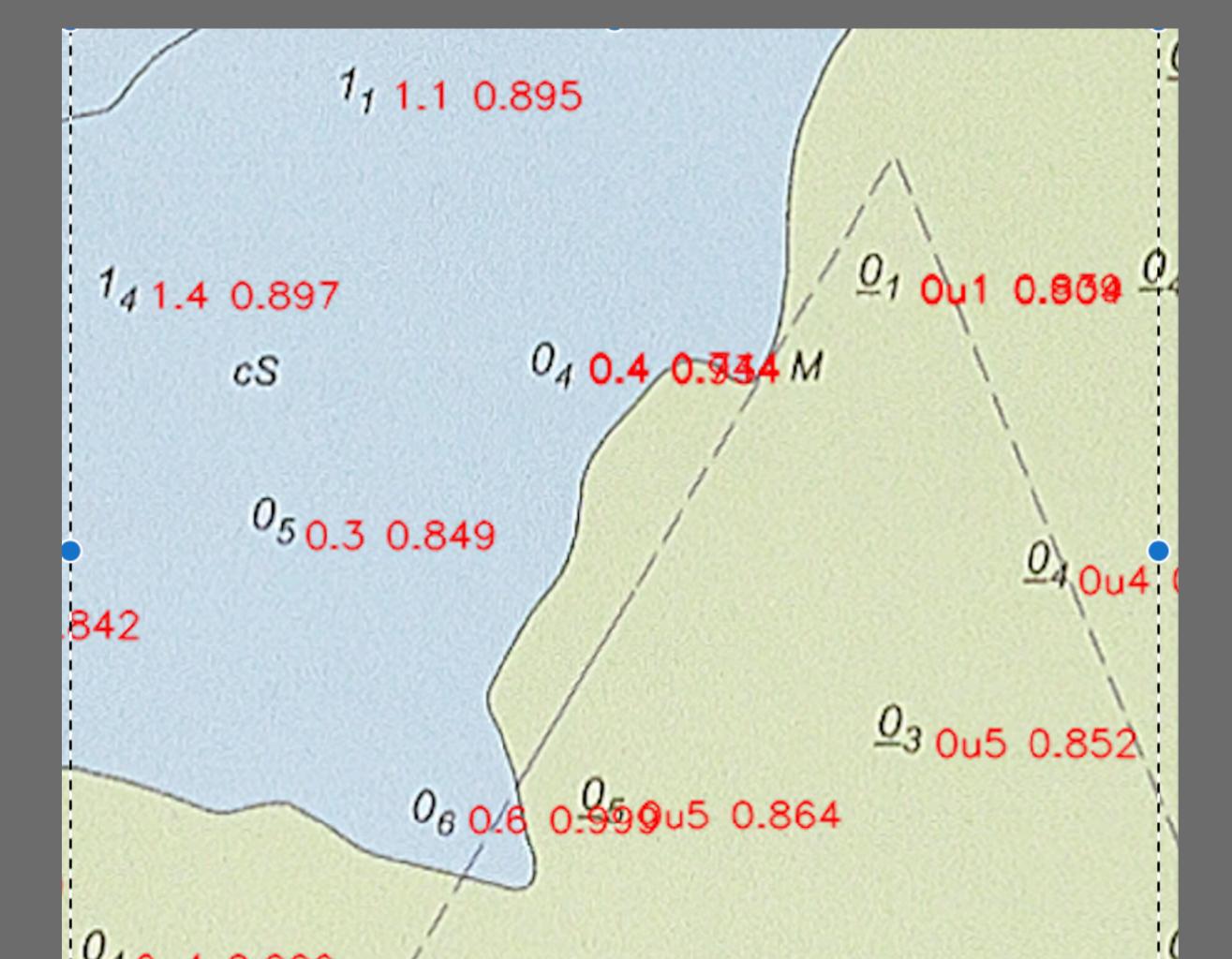
1. Make templates:



- 2. Make config file: Pick an optimal threshold for each template
- 3. Match templates using the suitable method in opency
- 4. Deal with the confusions

```
(13,) points are detected as 0.1
(8,)
     points are detected as
(12,) points are detected as
                              0.3
(20,) points are detected as
                              0.4
(18,) points are detected as
                              0.5
                              0.6
(12,) points are detected as
(17,) points are detected as
                              0.7
(2,) points are detected as
                             10.2
(1,) points are detected a
                           (13,) points are detected as
(1,) points are detected a
(8,) points are detected a 4049 , 2436
                           4194 , 2497
(10,) points are detected
                           2688 , 2506
                           4072 , 2513
                           4098 , 2645
                           4121 , 2862
                           4360 , 3566
                           4546 , 3587
                           3313 , 3854
                           32 , 3895
                           4173 , 5132
                           4273 , 5200
                           877 , 6864
```





# Long/Lat conversion

```
0.88 (0, 0, 255)
(13,) points are detected as 0.1
4194 , 2497
2688 , 2506
4072 , 2513
4098 , 2645
4121 , 2862
4360 , 3566
4546 , 3587
3313 , 3854
32 , 3895
4173 , 5132
4273 , 5200
B77 , 6864
0.2
0.88 (0, 0, 255)
(8,) points are detected as 0.2
```

```
- botton_leff_lon: <9 56.40>

<IN2004_Kochi_Harbour.tif>:
- width: <number of pixels>
- height: <number of pixels>
- top_left_lat: <76 18.00>
- top_left_lon: <10 02.40>
- bottom_left_lat: <76 04.60>
- botton_leff_lon: <9 53.80>

<40.png>:
- width: 23810
- height: 15164
- top_right_lat: <67 00.21>
- top_right_lon: <24 51.12>
- bottom_leff_lon: <24 51.12>
- bottom_leff_lon: <24 44.26>
```

```
DMS 67 00 13
DM.m 67 00.21
D.d 67.0035
```

The formulas are as follows:

#### Degrees Minutes Seconds to Degrees Minutes.m

```
Degrees = Degrees
Minutes.m = Minutes + (Seconds / 60)
```

#### Degrees Minutes.m to Decimal Degrees

```
.d = M.m / 60
Decimal Degrees = Degrees + .d
```

Find the number of degrees per image pixel size

# Moorfields Eye hospital

- Categorisation and relation extraction in Glaucoma related letters from Moorfields Eye hospital
- About 650k Letter with mention of the word "Glaucoma"
  - A. Categorise Glaucoma related letters vs Non-Glaucoma letter
  - B. Extract the correct information for the right and left eye, ie. relation extraction from highly unstructured text

A glaucoma follow up appointment

Diagnosis:

High myopia both eyes

Normal pressure glaucoma suspect both eyes

Previous cataract surgery

Examination:

Visual acuity 6/9 glasses right 6/6 left

The intraocular pressure measured 18mmHg in both eyes

Impression:

Tilted myopic discs. Thinning of neuroretinal rims. Stable superior arcuate scotoma left and enlarged blind spot right. She is happy to continue on topical medications as normal tension glaucoma cannot be ruled out.

Treatment:

The treatment that has been prescribed: G. timolol BD both eyes until review

Follow up:

A follow up has been arranged in 1 year.

A glaucoma follow up who also has AMD

The above patient was <u>reviewedin</u> the glaucoma clinic today. She has had an FFA in June and has bilateral PEDs. She does not seem to be under MR follow up. She has narrow angles as well as OHT. Please would you review her.

Visual acuity: Right eye 6/36 left eye 5/36 IOP: Right eye 14mmHg, left eye 17mmHg

Optic disc: Right eye 0.2, left eye 0.2

The treatment has been changed to latanoprost nocte bothe eyes. IOP is well controlled.

Treatment: please continue

The patient will be reviewed in 6 months time.

A glaucoma follow up appointment

Diagnosis

Primary open angle glaucoma

Right eye blind (old injury)

Pressures are much improved today at R13 and L15 on the current system of drops administered by a carer. The left eye has been stable for many years.

Investigations: Feids left eye stable stable 20 years with subtle arcuate defect

Medications prescribed: Continue latanoprost BE nocte

Follow up: review in 6 months with fields

### **NLP Toolkits and Libraries**

- TextBlob
  - Sentiment Analysis, Noun phrase detection, translation using Google API, etc.
- Spacy
  - Industrial-strength Nlp, Name Entity Recognition, Dependency parsing
  - Built-in visualiser for syntax and NER
- NLTK
  - Interfaces to WordNet and other resources, parsers, tokenisers, semantic reasoning

#### Relation Extraction

- Extracting structured information from unstructured sources such as raw text.
- Chunking and noun phrase extraction, Part-of-speech tagging, parsing
- Steps required: Entity Linking (Co-reference analysis)
- DeepDive project@Stanford

## Project Works: ML focus

- Natural language processing
  - Translation, relation extraction, name entity recognition, sentiment analysis
- Image processing
  - Digit recognition, segmentation, object detection
- Al in Healthcare
  - Medical imaging, Electronic record analysis, data-driven predictions
- Deep learning methods & tools for big datasets
  - Using state-of-the-art toolkits such as TensorFlow & Keras
- Reinforcement learning application

## **Training Activities**

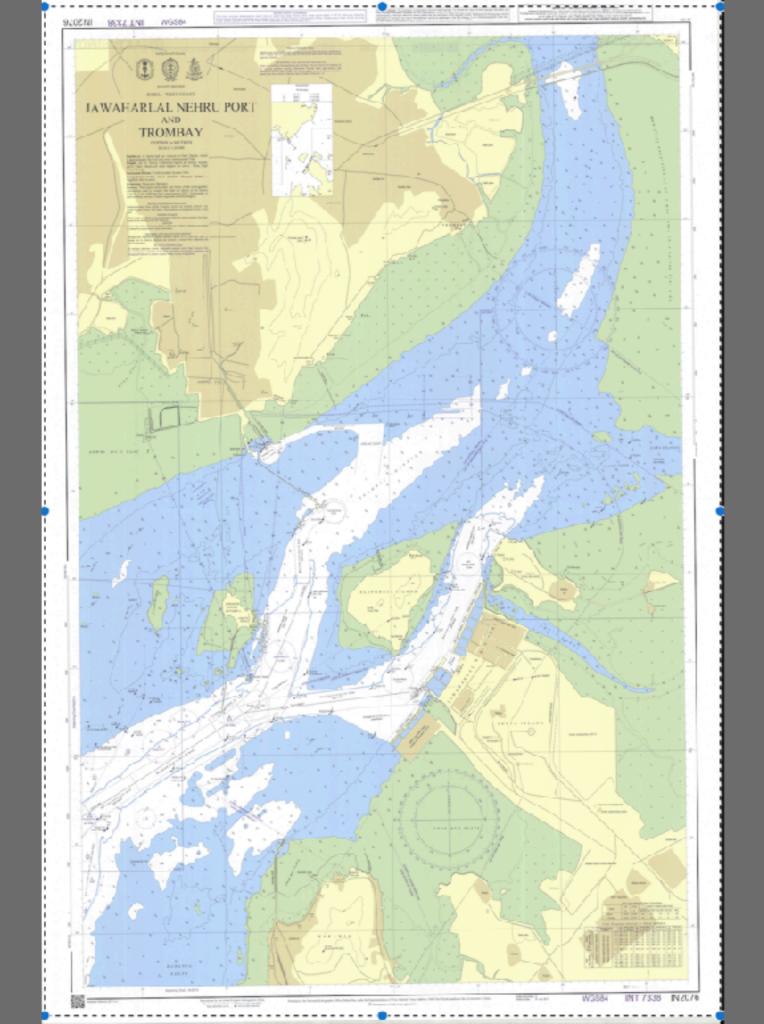
- Software and Data Carpentry
- Centre for Doctoral Training (CDT) Data Intensive Science track
  - Intent modelling for ASOS Chat Data
- Crick Network Fund:

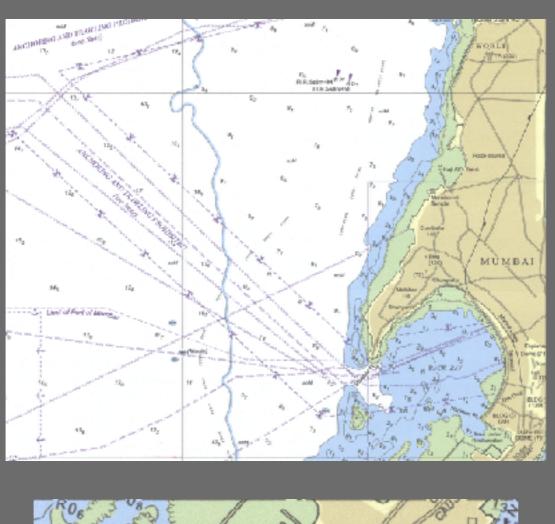
"Building a Knowledge Exchange Hub for data-driven and machine learning-based large-scale biomedical image analysis", with Imperial and Kings College London.

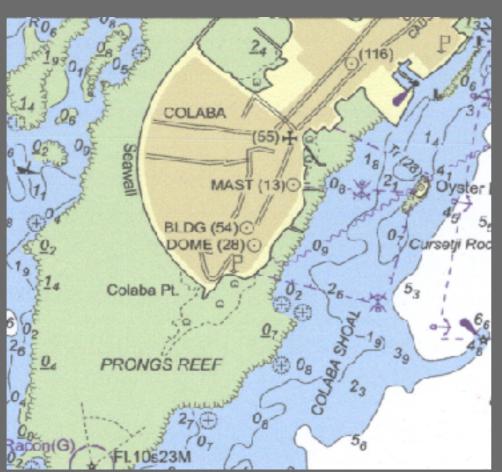
# How to find us

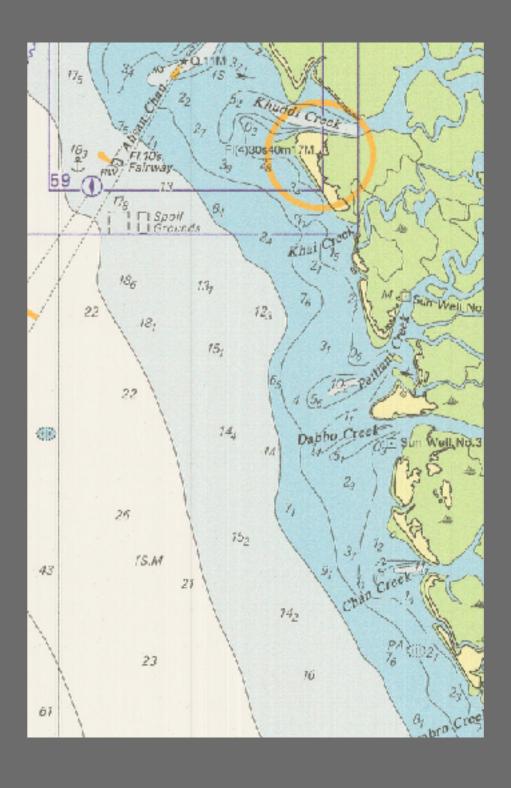
- Email me: "s.jabbari@ucl.ac.uk"
- Email: "rc-softdev@ucl.ac.uk"
- Level 6, 1-19 Torrington PI, Fitzrovia, London WC1E 7HB

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# Al in Physics

#### Particle Physics:

- One of the biggest physics discoveries, the Higgs boson particle or "God particle", was discovered using the neural network.
- Large Hadron Collider (LHC), largest particle accelerator in the world, in an hour it generates approximately as much data as Facebook handles in a year.

### Objection Detection Evaluation Metric

- the Average Precision (AP) metric is a summary of the precision-recall curve
- Commonly used metric used for object detection challenges is called the mean Average Precision (mAP)
- The mAP metric avoids to have extreme specialisation in few classes and thus weak performances in others.
- The mAP score is usually computed for a fixed IoU (Intersection over Union)