

# In Action Execution and Observation the Cerebellum Exerts a Differential Control over the Excitatory/Inhibitory Dynamics of Inter-Regional Effective Connectivity

Gökçe Korkmaz<sup>1,3</sup>, Roberta M. Lorenzi<sup>1</sup> Adnan A.S. Alahmadi<sup>2,3</sup>, Anita Monteverdi<sup>4</sup>, Letizia Casiraghi<sup>1,5</sup>, Egidio D'Angelo<sup>1,4</sup>, Fulvia Palesi<sup>1</sup>, Claudia A.M. Gandini Wheeler-Kingshott<sup>1,3,4</sup>

<sup>1</sup>Department of Brain and Behavioral Sciences, University of Pavia, Pavia, Italy <sup>2</sup>Department of Radiologic Sciences, Faculty of Applied medical sciences, King Abdulaziz University, Jeddah, Saudi Arabia

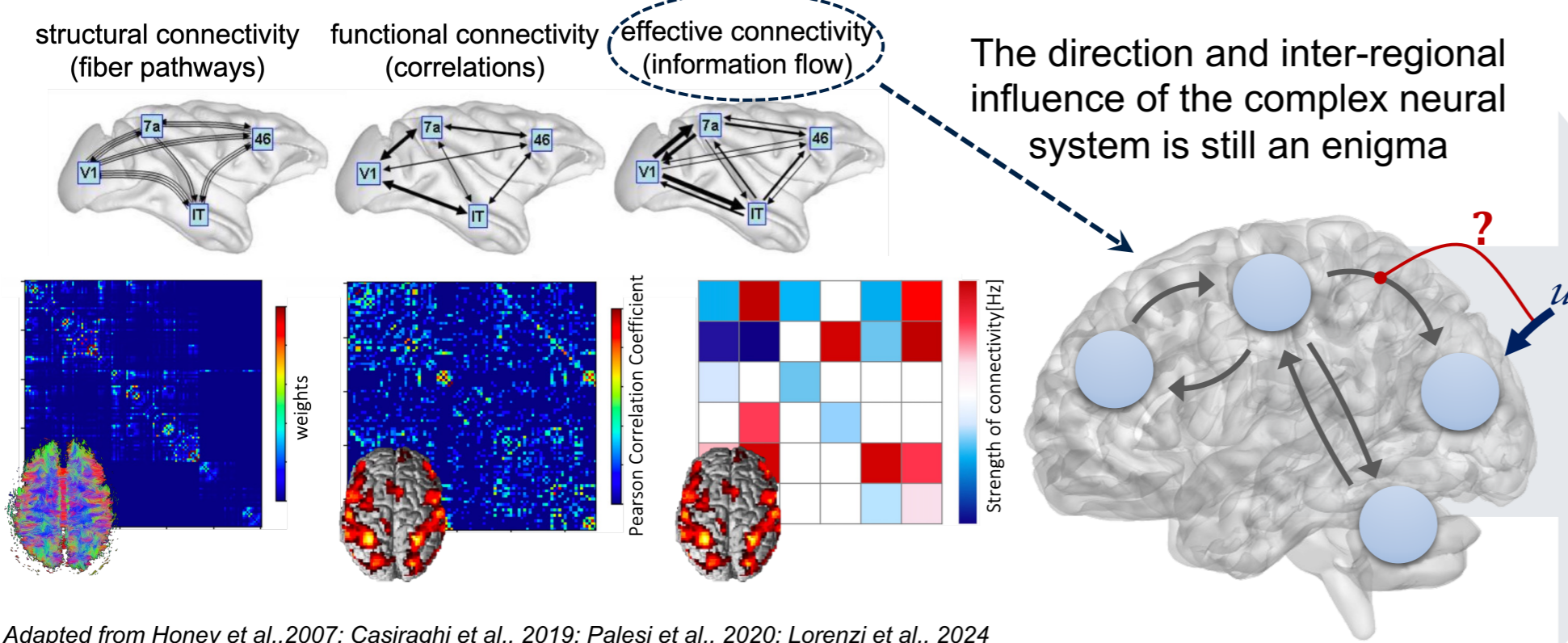
<sup>3</sup>NMR Research Unit, Queen Square Multiple Sclerosis Centre, Department of Neuroinflammation, UCL Queen Square Institute of Neurology, UCL, London, UK

<sup>4</sup>Digital Neuroscience Center, IRCCS Mondino Foundation, Pavia, Italy <sup>5</sup>Department of Mental Health and Dependence, ASST of Pavia, Pavia



Introduction

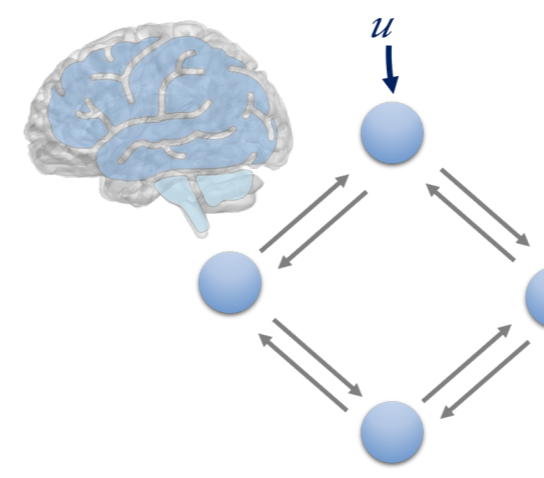
## A step further to explain brain connectivity



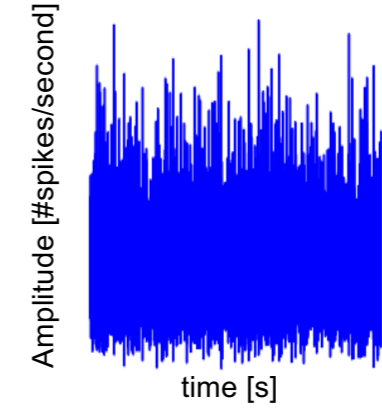
Adapted from Honey et al., 2007; Casiraghi et al., 2019; Palesi et al., 2020; Lorenzi et al., 2024

## Dynamic Causal Modelling (DCM)

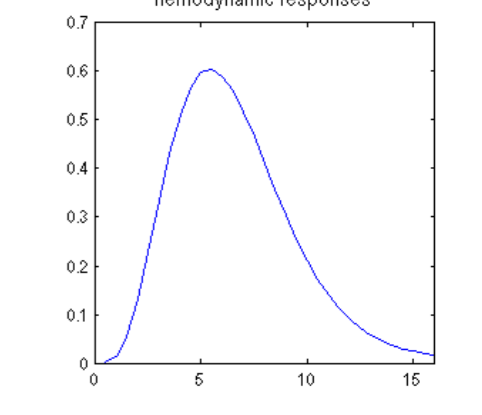
DCM goal is to uncover the underlying neural mechanisms of causal interactions by quantifying the effective connectivity between regions



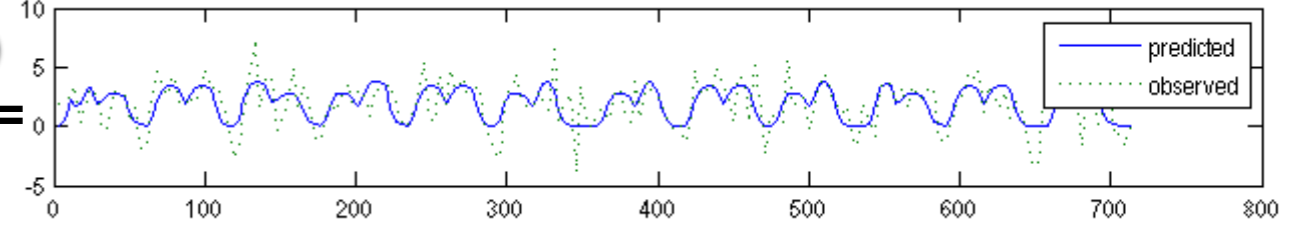
## Neuronal Model



## Haemodynamic Model



Blood Oxygenation Level Dependent (BOLD) signal



The neuronal model represents the neural activity that drives dynamic interactions between brain regions and that is linked to the BOLD signal through an hemodynamic model.

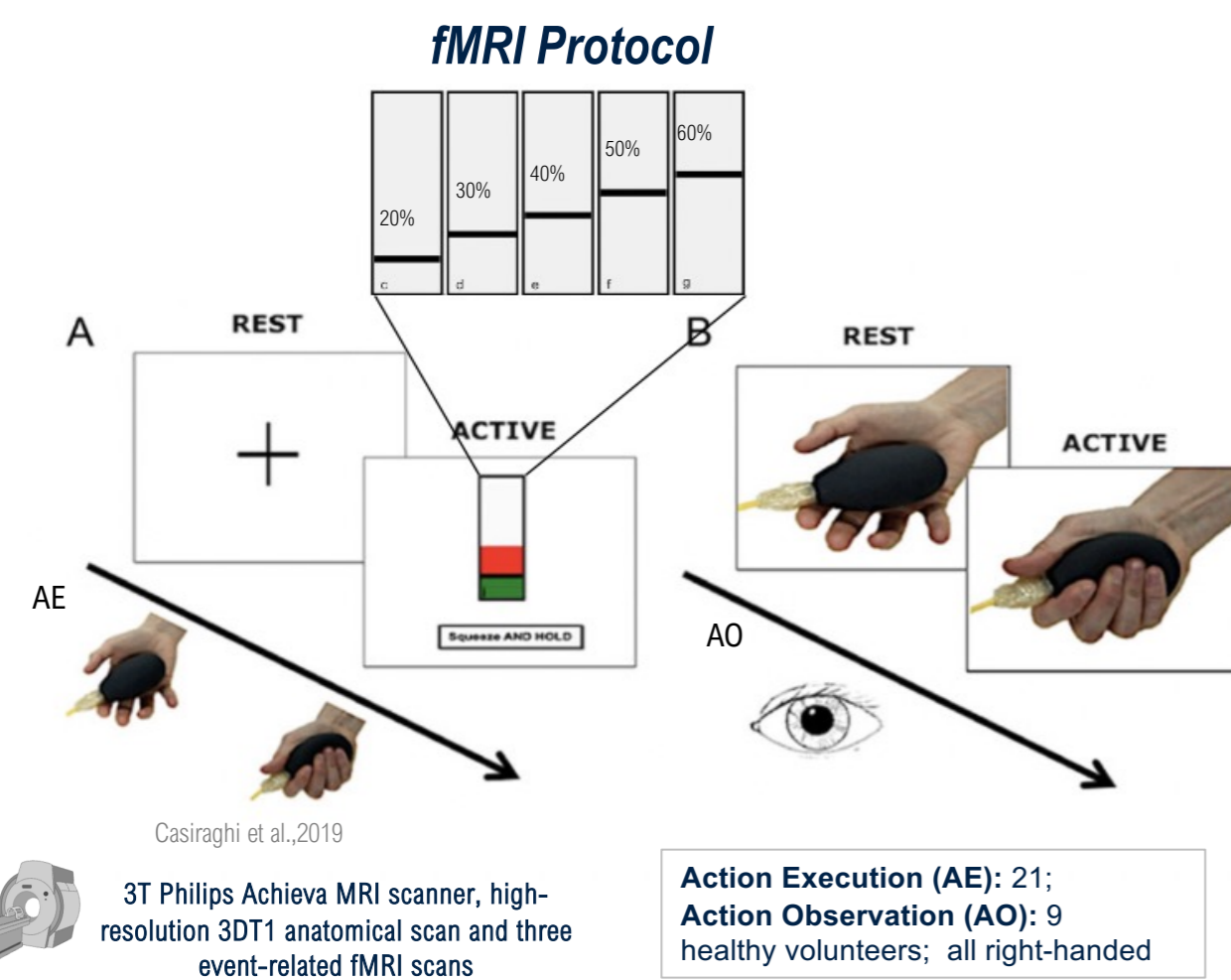
Goal

**AIM: Unveiling the differences in Cerebro-Cerebellar causal relations during Action Execution (AE) and Action Observation (AO)**

Methods

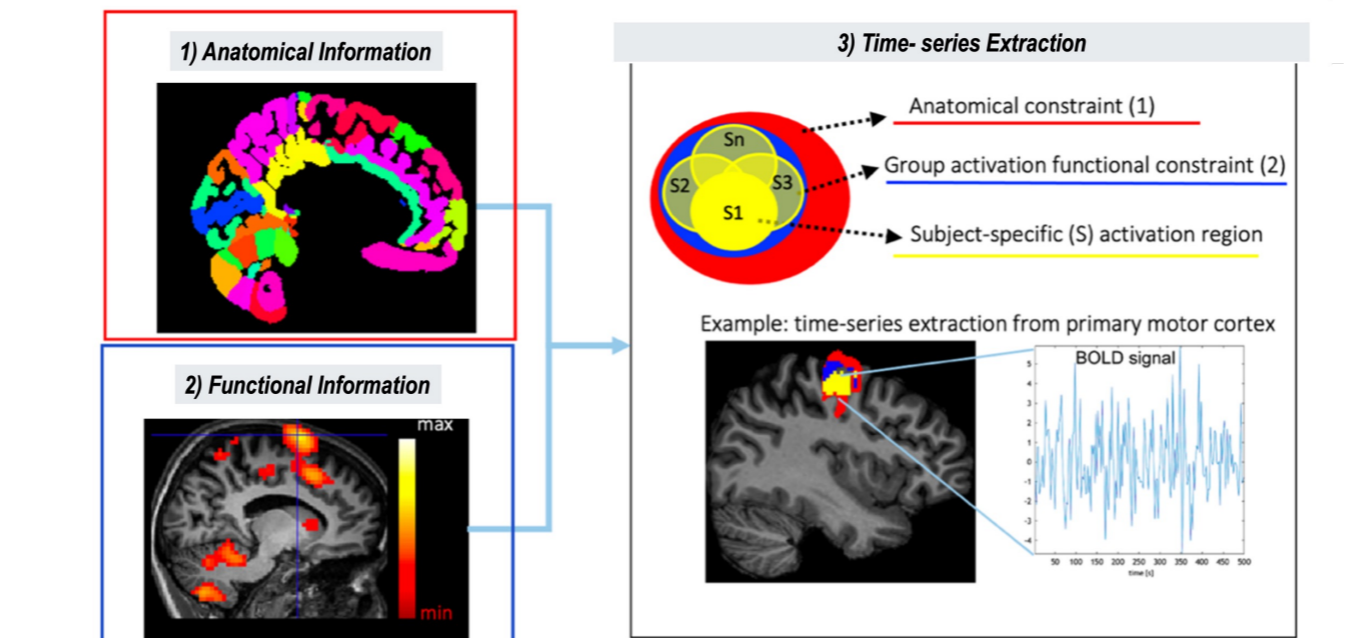
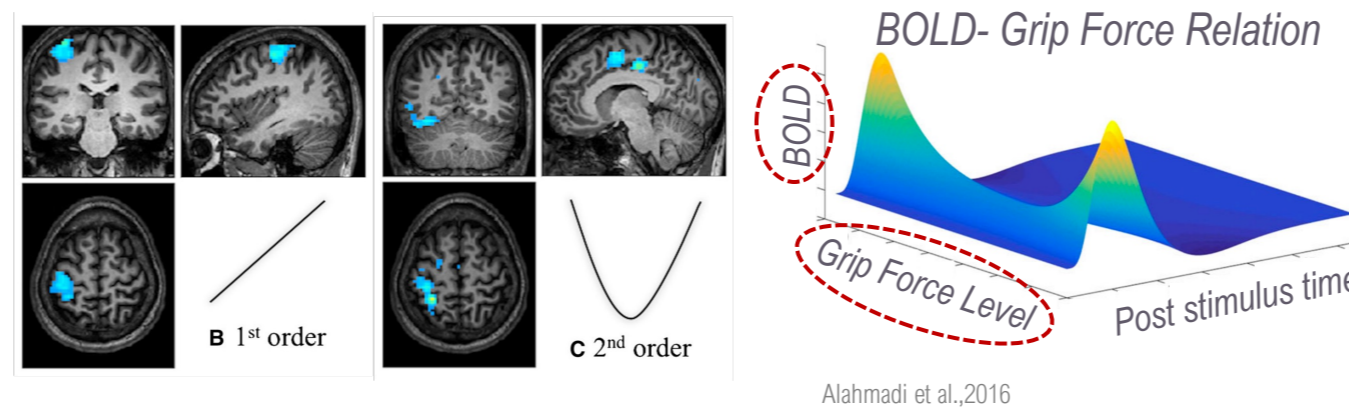
## Grip Force and BOLD Response

We aimed to identify and quantify regional BOLD responses to Grip Force variations when performing and observing a squeeze ball task



3T Philips Achieva MRI scanner, high-resolution 3DT1 anatomical scan and three event-related fMRI scans  
Action Execution (AE): 21; Action Observation (AO): 9 healthy volunteers; all right-handed

## Investigating Linear and Non-linear Responses

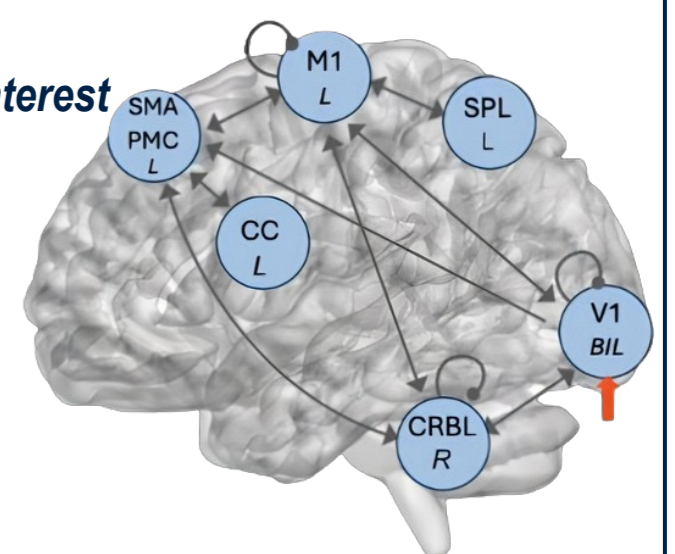


Time-series were extracted by doing a conjunction analysis

## Model Construction

### Visuomotor Network - Regions of Interest

V1\_BIL: Bilateral primary visual cortex  
M1\_L: Left primary motor cortex  
CC\_L: Left cingulate cortex  
SPL\_L: Left superior parietal lobule  
SMAPMC\_L: Left supplementary motor area & premotor cortex  
CRBL\_R: Right cerebellum



### Step 1 (S1)

#### Direct influences:

How do the regions embedded in the visuomotor network influence each other in AE and AO?

### Step 2 (S2)

#### Nonlinear modulations:

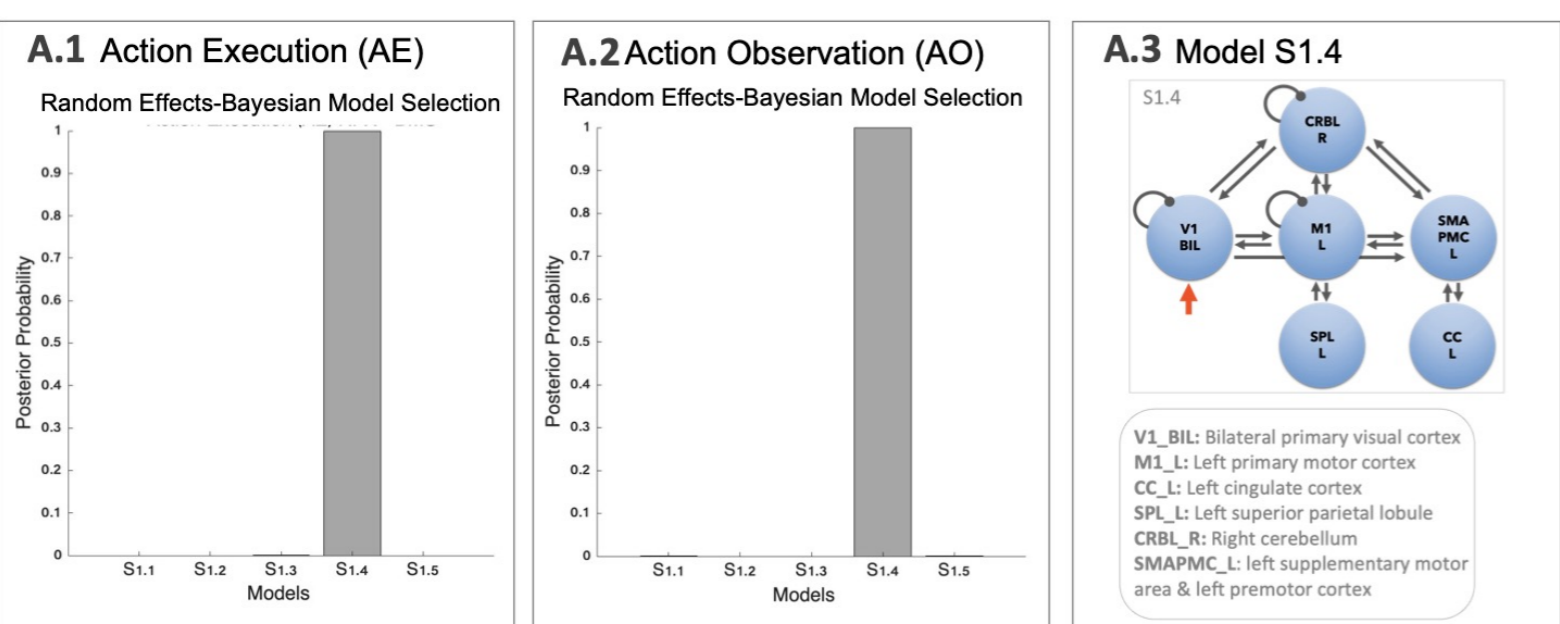
Who drives the non-linearities in the visuo-to-plan functional pathway?

By comparing different causal models, Bayesian Model Selection (BMS) determined the most likely causal architecture that best explains the observed data

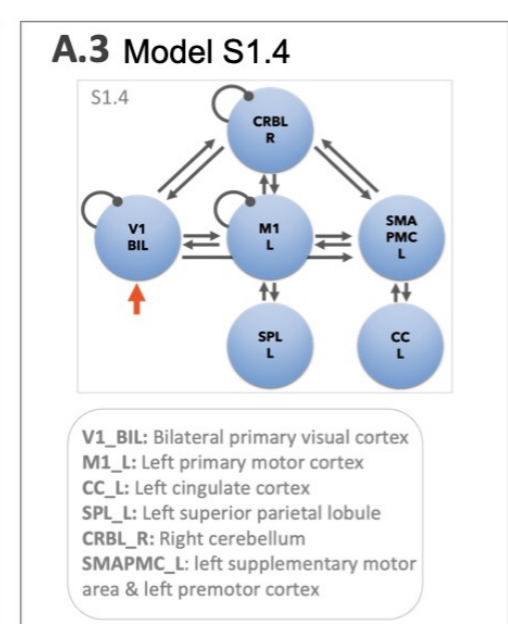
Results

## Fixed Effective Connectivity winning model (S1 outcomes)

### A) Bayesian Model Selection

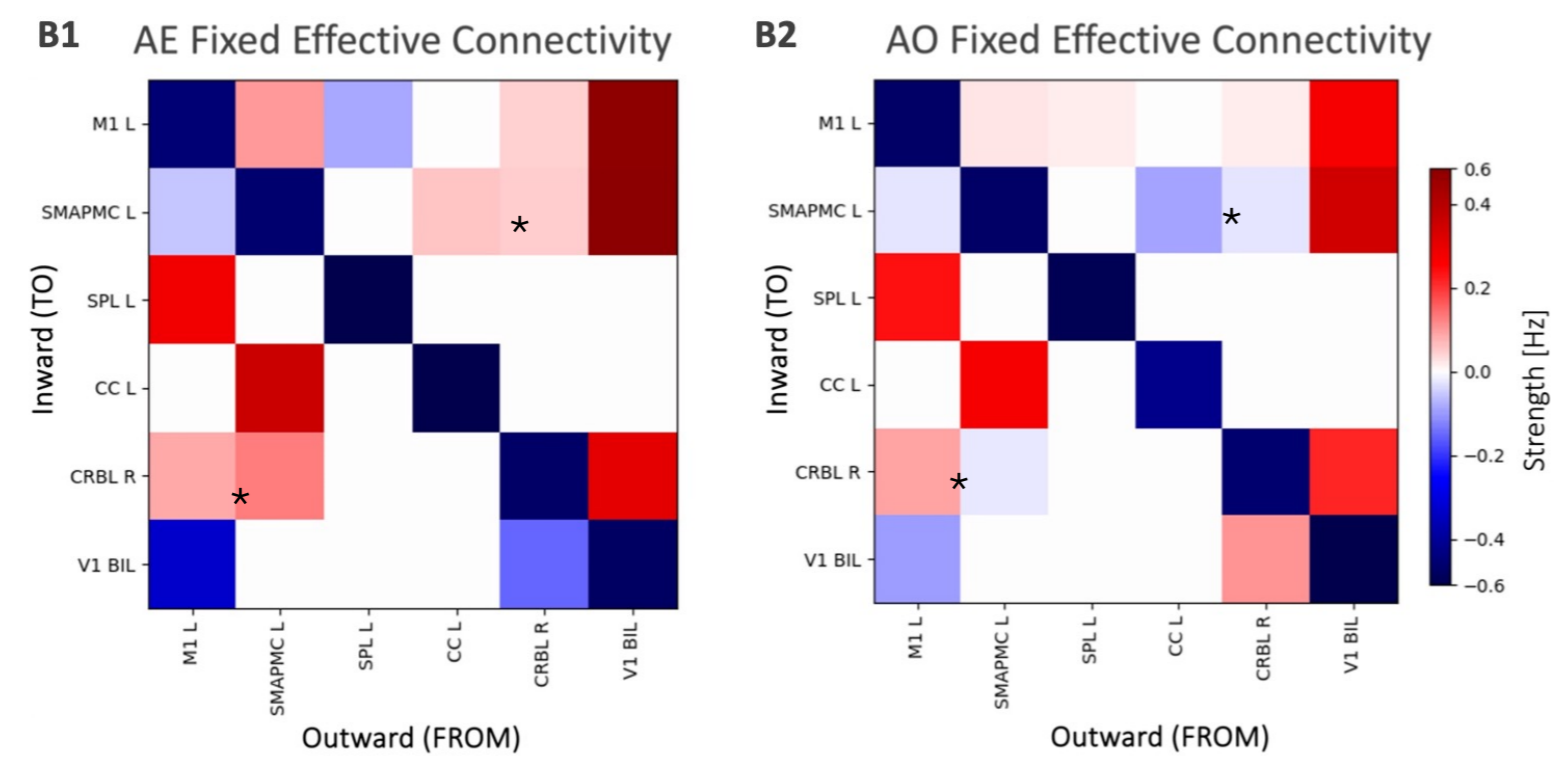


### Winning model structure



BMS with random effects (RFX-BMS) identified Model S1.4 as the "winning model" with posterior probability > 90% in both action execution (AE, panel A.1) and action observation (AO, panel A.2).

### B) Fixed Effective Connectivity

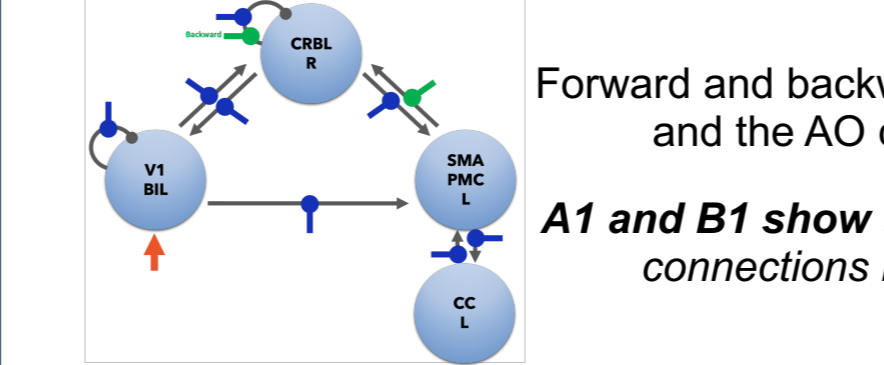


Effective connectivity strength in Hz with positive values for excitatory connections and negative values for inhibitory connections.

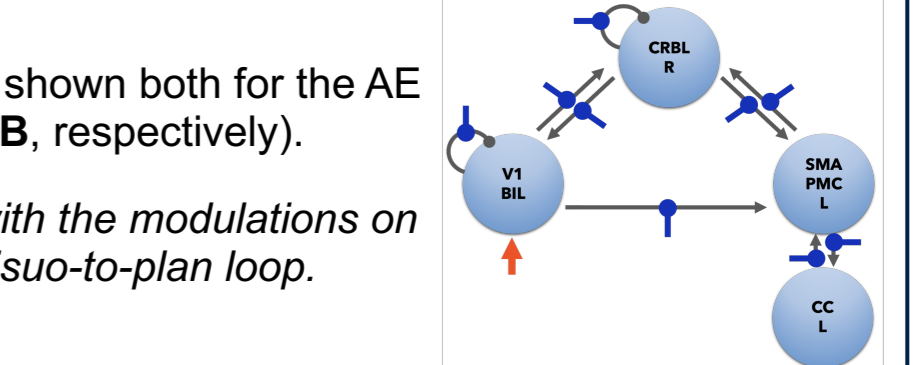
The strongest excitatory connections are from V1 to SMAPMC, both in AE and AO, and from V1 to M1 only in AE. The connections CRBL-R → SMAPMC-L and SMAPMC-L → CRBL-R are excitatory in AE while they are inhibitory in AO

## Modulation of the Fixed Effective Connectivity (S2 outcomes)

### A1) Action Execution (AE) Network

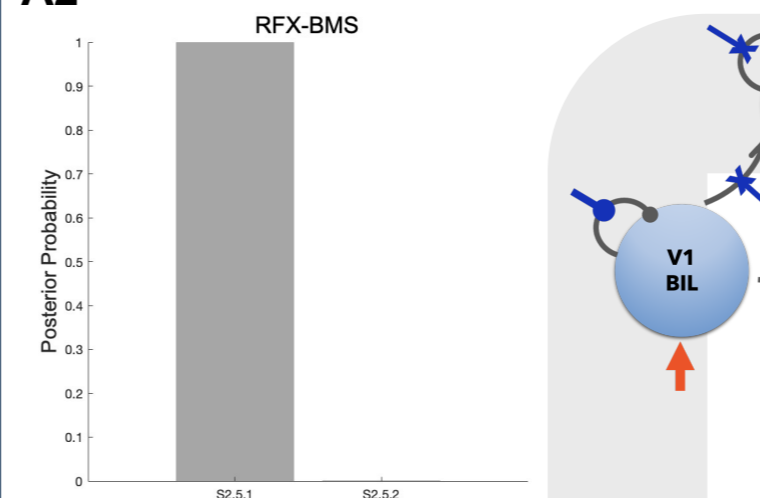


### B1) Action Observation (AO) Network

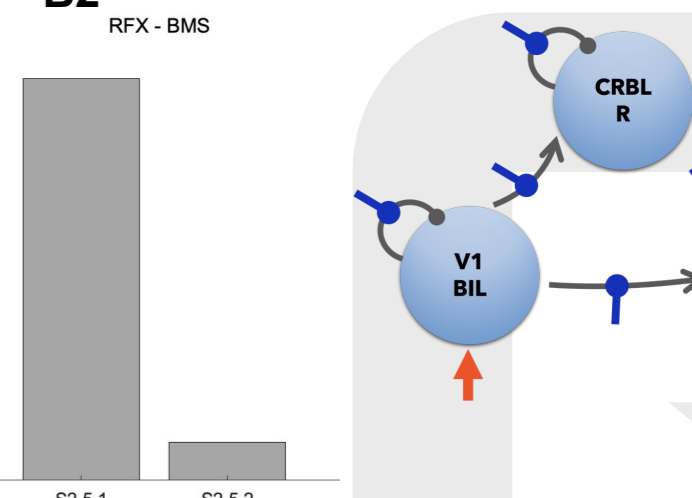


Forward and backward winning models are shown both for the AE and the AO conditions (Panel A and B, respectively).  
A1 and B1 show the S2-winning models with the modulations on connections between regions of the visuo-to-plan loop.

### A2) Forward Pathway

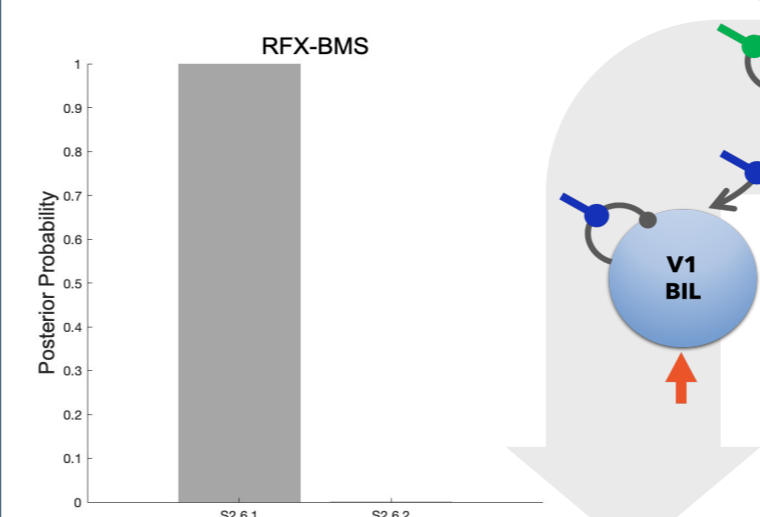


### B2) Forward Pathway

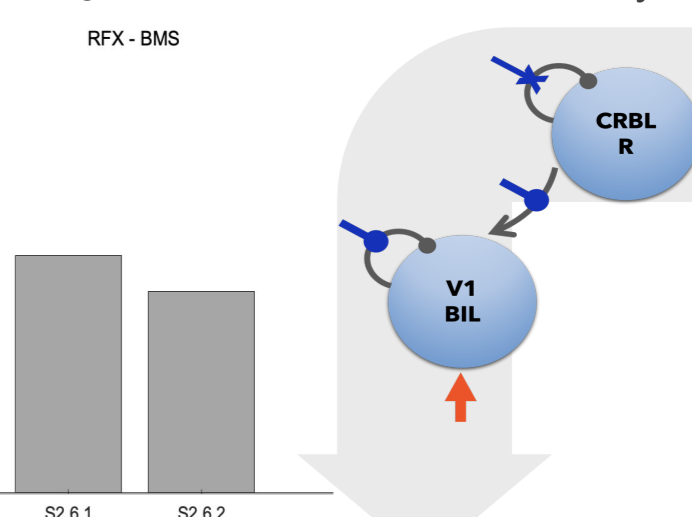


A2 - B2 & A3 - B3) Each histogram shows the posterior probability resulting from RFX-BMS and a schematic representation of the S2-winning model for AE and AO forward loops (A2 & B2) and backward loops (A3 & B3).

### A3) Backward Pathway



### B3) Backward Pathway



Connections between regions ↑ Driving input ↓ 1st order modulation with inhibition of the connection strength [Hz]

↑ 1st order modulation with excitation of the connection strength [Hz]

↑ 2nd order modulation with excitation of the connection strength [Hz]

The Cerebellum regulates BOLD modulations nonlinearly in AE and linearly in AO.

Conclusion

**The presence of sensorimotor feedback in AE determines the way the cerebellum operates as a forward controller on motor planning areas.**

Our next step will be investigating how sensorimotor control impacts on cerebro-cerebellar function and dysfunction in neuroinflammatory diseases such as Multiple Sclerosis (MS)

## References

1. Friston et al., 2003. Neuroimage. 2. Penny et al., 2010. PLoS Computational Biology. 3. Alahmadi et al., 2016. Brain Structure and Function. 4. Casiraghi et al., 2019. Cerebral Cortex.

Gökçe Korkmaz

goekce.korkmaz01@universitadipavia.it  
g.korkmaz@ucl.ac.uk  
LinkedIn/GökçeKorkmaz

