Profiling GPU Code

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What is Profiling?

Measuring Performance

- Measuring application performance
 - Usually the aim is to reduce runtime
- Simple profiling:
 - How long does an operation take?
- Advanced profiling:
 - Why does an operation take a long time?

Profiling Workflow

- 1. Find which parts of the code take time
- 2. Work out why they take time
- 3. Optimize
- 4. GOTO 1.

GPU Performance

Quick overview

- A processor has two key performance limits
 - Floating point throughput (FLOP/s)
 - Peak ~6 TFLOP/s
 - Memory throughput (GB/s)
 - Peak ~300 GB/s (DRAM)
- GPUs also need parallelism
 - This is how they can be so fast

Profiling Tools

General GPU Profiling

From NVIDIA

- nvprof
- NVIDIA Visual profiler
 - Standalone (nvvp)
 - Integrated into Nsight Eclipse Edition (nsight)
- Nsight Visual Studio Edition

Third Party

- Tau Performance System
- VampirTrace
- PAPI CUDA component

In this talk

- We will focus on nvprof and nvvp
- NVIDIA Profiler
 - Command line
- nvvp => <u>NV</u>IDIA <u>V</u>isual <u>P</u>rofiler
 - GUI based



Case Study

Recurrent Neural Network - LSTM

- Uses:
 - Natural language processing
 - Sequences of images (eg. video)
 - Bio/medical
- We will look at optimisation of a single iteration of LSTM



LSTM Viewed as a black box



- Inputs and outputs are "batched vectors".
 - ie. A minibatch
- Typical length is 256-2048
- Typical batch size is 32-128

LSTM Details



LSTM Profile Using nvprof

>> nvprof ./RNN 512 64							
==6805== NVPROF is profiling process 6805, command: ./RNN 512 64							
==6805== Profiling application: ./RNN 512 64							
==6805==	Profiling	result:					
Time(%)	Time	Calls	Avg	Min	Max	Name	
88.46 %	512.07us	8	64.009us	60.449us	75.618us	maxwell_ sgemm _128x64_tn	
4.26%	24.673us	8	3.0840us	2.9120us	4.1600us	<pre>pw_biasAdd(float*, float*, int, int)</pre>	
1.93%	11.200us	5	2.2400us	2.0160us	2.9760us	<pre>pw_vecAdd(float*, float*, float*, int)</pre>	
1.92%	11.136us	3	3.7120us	3.4560us	4.1920us	[CUDA memcpy DtoD]	
1.39%	8.0650us	3	2.6880us	2.3040us	3.4570us	<pre>pw_sigmoid(float*, float*, int)</pre>	
1.15%	6.6560us	3	2.2180us	1.9840us	2.6560us	<pre>pw_vecMul(float*, float*, float*, int)</pre>	
0.88%	5.0880us	2	2.5440us	2.3040us	2.7840us	<pre>pw_tanh(float*, float*, int)</pre>	

LSTM Profile Using nvvp

- Can run interactively
- Or use nvprof -o a.nvp and import file

🖃 [0] Tesla M40									
Context 1 (CUDA)									
🗆 🍸 MemCpy (DtoD)									
Compute	maxwell_s	maxwel	maxwell	maxwell	maxwell	maxwell	maxwel	maxwel	
L 🍸 90.2% maxwell_sgemm_12	maxwell_s	maxwel	maxwell	maxwell	maxwell	maxwell	maxwel	maxwel	
└ 🍸 4.4% pw_biasAdd(float*, fl									
└ 🍸 1.9% pw_vecAdd(float*, fl									
└ 🍸 1.5% pw_sigmoid(float*, fl									
└ 🍸 1.2% pw_vecMul(float*, flo									
└ 🍸 0.9% pw_tanh(float*, float*									
Streams									
L Default	maxwell_s	maxwel	maxwell	maxwell	maxwell	maxwell	maxwel	maxwel	

Back of the envelope

- SGEMM is a well known operation
- With the inputs chosen each should perform about 33 million floating point operations
- 33 million / 64us = ~516 GFLOPs.
 - GPU can do ~6000 GFLOPs!
- What is wrong?

What is wrong?

- Collect performance metrics:
 - Either via nvprof --analysis-metrics ...
 - Or interactively
- A lot of information available
 - Guided analysis helps filter this down
 - Leads me to: "Optimization: Increase the number of blocks executed by the kernel."
 - Expose more parallelism!

Improvement #1

 $[A_{1}][h] = [y_{1}]$ $[A_{2}][h] = [y_{2}]$ $[A_{3}][h] = [y_{3}]$ $[A_{4}][h] = [y_{4}]$

As our matrix operations share inputs we can combine them

Improvement #1

Before:

 Time(%)
 Time
 Calls
 Avg
 Min
 Max
 Name

 88.46%
 512.07us
 8
 64.009us
 60.449us
 75.618us
 maxwell_sgemm_128x64_tn

After:

 Time(%)
 Time
 Calls
 Avg
 Min
 Max
 Name

 75.97%
 213.19us
 2
 106.59us
 104.90us
 108.29us
 maxwell_sgemm_128x64_tn

SGEMM Performance Improvement #2

- We are still doing two independent matrix products
 - We can combine them
 - Or compute them simultaneously

$$\begin{bmatrix} A_1 \\ A_2 \\ A_3 \\ A_4 \end{bmatrix} \begin{bmatrix} h \end{bmatrix} = \begin{bmatrix} y \\ y \\ B_1 \\ B_2 \\ B_3 \\ B_4 \end{bmatrix} \begin{bmatrix} i \end{bmatrix} = \begin{bmatrix} z \\ z \\ B_4 \end{bmatrix}$$

Improvement #2

- We are still doing two independent matrix products
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 - Or compute them simultaneously

$$\begin{bmatrix} A_1 \\ A_2 \\ A_3 \\ A_4 \end{bmatrix} \begin{bmatrix} h \end{bmatrix} = \begin{bmatrix} y \\ y \\ d_4 \end{bmatrix} \begin{bmatrix} B_1 \\ B_2 \\ B_3 \\ B_4 \end{bmatrix} \begin{bmatrix} i \end{bmatrix} = \begin{bmatrix} z \\ z \\ B_4 \end{bmatrix}$$

Matrix overlapping



Final optimization

Fuse element-wise operations



LSTM Performance

Optimisation	Runtime	Speedup
Naïve	661us	(1.0x)
Combined matrices	357us	1.9x
Matrix streaming	250us	2.6x
Fused element-wise ops	136us	4.9x

Profiling 5x performance improvement

- Profiling helped to quickly identify the slow parts
- It showed that SGEMM was underusing the GPU
 - This was fixed by exposing more parallelism
- It showed that the pointwise operations were taking a significant proportion of our runtime
 - This was fixed by fusing them



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